

Supercharge me: Boost Router Convergence with SDN

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ABSTRACT

Software Defined Networking (SDN) is a promising approach for improving the performance and manageability of future network architectures. However, little work has gone into using SDN to improve the performance and manageability of existing networks without requiring a major overhaul of the existing network infrastructure.

In this paper, we show how we can dramatically improve, or *supercharge*, the performance of existing IP routers by combining them with SDN-enabled equipment in a novel way. More particularly, our supercharged solution substantially reduces the convergence time of an IP router upon link or node failure without inducing any reconfiguration of the IP router itself. Our key insight is to use the SDN controller to precompute backup forwarding entries and immediately activate them upon failure, enabling almost immediate data-plane recovery, while letting the router converge at its typical slow pace. By boosting existing equipment’s performance, we not only increase their lifetime but also provide new incentives for network operators to kickstart SDN deployment.

We implemented a fully functional “supercharger” and use it to boost the convergence performance of a Cisco Nexus 7k router. Using a FPGA-based traffic generator, we show that our supercharged router systematically converges within ~150ms, a 900× reduction with respect to its normal convergence time under similar conditions.

1. INTRODUCTION

By enabling logically-centralized and direct control of a network forwarding plane, Software-Defined Networking (SDN) holds great promises in terms of improving network management and performance, while lowering costs at the same time. Realizing this vision is challenging though as SDN requires major changes to a network architecture before the benefits can be realized [1]. This is problematic as existing networks tend to have a huge installed base of devices, management tools, and human operators that are not familiar with SDN, leading to significant deployment hurdles. As a result, the number of SDN deployments has been rather limited in scope; there have been efforts in private backbones [2, 3] and software deployments at the network edge [4].

In order to kickstart a wide-scale SDN deployment, we argue that operators need to be offered with SDN-based technologies possessing at least three key characteristics. First, the advantages of SDN should be readily apparent with only a *small deployment*. Ideally, benefits should be reaped with the deployment of a single SDN device; as comfort and enthusiasm increases, new SDN devices can be incrementally deployed. Second, they should be *low-risk*. In particular, they should require minimum changes to existing operational practices and should be compatible with currently deployed technologies. Finally, they should offer a *high return*, meaning the SDN-based technologies should solve a timely problem.

As an example of such a technology, we show how we can significantly improve the performance of existing IP routers, *i.e.* “supercharge” them, by combining them with SDN-enabled devices. Supercharging a router is a low-risk, high-reward operation. First, it provides operators with a strong incentives to deploy SDN-enabled device as they enable them to increase the lifetime of their routers, at a considerably lower cost than buying new ones¹. Second, supercharging a router does not change the existing router’s behavior, just its performance. Consequently, network operators can conveniently troubleshoot and maintain the original network. Third, once enough routers have been supercharged, those deployed SDN equipments can be used to implement a more disruptive SDN architecture.

In this short paper, we supercharge one particular aspect of the router performance: its convergence time after a link or a node failure. Current routers are often slow to converge after a link failure because of the time it takes to update their forwarding tables; this is an entry-by-entry process that can go on for potentially hundreds thousand of entries. Our key insight is that, by coupling together a router and a SDN switch, we can build a 2-stage forwarding table which spans across the two devices with a first lookup done in the router and the second one in the switch. With this type of

¹Current SDN switches are orders of magnitude cheaper than fully equipped routers.

(typically) OpenFlow to provision forwarding entries in a SDN switch, dynamically provisioning specific forwarding entries in a router is trickier. Our key insight is that the supercharged controller can use any routing protocol spoken by the router as a provisioning interface. Indeed, FIB entries in a router directs traffic to the L2 NH associated to the L3 NH learned via the routing protocol. Our supercharged controller interposes itself between the router and its peers (we explain how to make this reliable in §3), computes primary and backup NH for all IP destinations, and provisions L2 NH “pointers” by setting the IP NH field to a virtual L3 NH that gets resolved by the router into a L2 NH using ARP. Upon failure of $R2$ in Fig. 2, all the controller has to do to convergence is to modify the switch rule to (rewrite(00:ff) to (02:bb,2)) in order to converge *all traffic* to $R3$.

Contributions. We make the following contributions:

- **Supercharging router convergence:** We propose novel ways to combine SDN and legacy networking equipment to improve convergence times (§2).
- **Implementation:** We describe a fully working prototype implementation of a supercharger controller, combining OpenFlow/Floodlight and ExaBGP (§3). Our implementation is efficient, reliable, and can be used to supercharge *any* router.
- **Hardware-based Evaluation:** We supercharged a hardware router (Cisco Nexus 7k) and thoroughly evaluated its performance (§4). To ensure precise measurements, we developed a FPGA-based traffic generator which detects traffic loss within $70\mu s$. With respect to the normal router convergence under similar conditions, the supercharged version converged systematically within 150ms, a $900\times$ reduction!

2. SUPERCHARGING CONVERGENCE

In this section, we describe how to supercharge the convergence of any existing router using SDN equipment to build a hierarchical forwarding table.

Overview. Since the number of destinations is much greater than the number of neighbors, many destinations (IP prefixes) will share the same primary and backup NH. We refer to the couple (primary NH, backup NH) as *backup-group*. For instance, in Fig. 2, all 512k prefixes share ($R2, R3$) as backup-group. If $R2$ fails, all entries will be rewritten to point to $R3$.

In a supercharged router, we use the router to *tag* the traffic according to the backup-group it belongs to and use the switch to *redirect* the tagged traffic to the master or backup NH depending on its status. We use the destination MAC address as the tag and provision it in the router using the virtual NH field in routing announcements. Fig. 3 depicts the overall architecture.

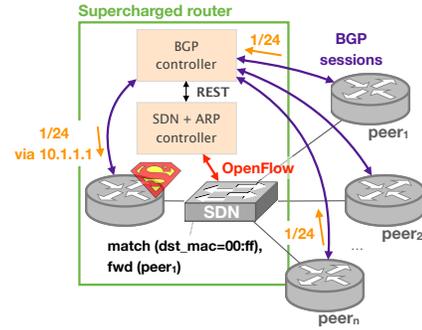


Figure 3: Supercharged router overview

Provisioning *tagging entries* in the router’s FIB.

To provision entries in the router’s FIB, a routing daemon is interposed between the router and its peers. Its role is to compute the backup-groups for every IP destination. For simplicity, we assume that BGP is used as routing protocol, but other intra-domain routing protocols such as OSPF or IS-IS can also be used [12]. The routing daemon assigns a Virtual IP NH (VNH) and a corresponding virtual MAC (VMAC) address to each distinct backup-group and rewrites the routing NH in the corresponding announcements that it directs to the supercharged router. In Fig. 3, the backup-group for 1.0.0.0/24 is ($peer_1, peer_n$) and the corresponding (VNH, VMAC) is (10.1.1.1, 00:ff). Upon reception of a route associated with a VNH, the router issues an ARP request to resolve it to a MAC address. This ARP request is caught by the SDN controller which replies with the corresponding VMAC address. After that, the supercharged router will use the VMAC as the destination MAC for all the corresponding traffic sent in the data-plane.

```
bck_groups = {}
routing_table = {}
```

```
def compute_backup_groups(bgp_upd):
    old = routing_table[bgp_upd.pfx]
    insert(routing_table, bgp_upd)
    new = routing_table[bgp_upd.pfx]
```

```
if old:
    if not new:
        send_withdraw(bgp_upd.pfx)
    else:
        if new != old:
            if len(new) == 1:
                send(bgp_upd)
            else:
                if (new[0].nh, new[1].nh) != (old[0].nh, old[1].nh):
                    if new[0].nh not in bck_groups:
                        bck_groups[new[0].nh] = {}
                    if new[1].nh not in bck_groups[new[0].nh]:
                        bck_groups[new[0].nh][new[1].nh] = get_new_vnh_vmac()
                    rewrite_nh(bgp_upd, bck_groups[new[0].nh][new[1].nh].nh)
                    send(bgp_upd)
        else:
            send(bgp_upd)
```

Listing 1: Online algorithm computes backup-group

Computing backup-groups. Listing 1 describes an online algorithm for computing the backup-group. In essence, the algorithm maintains an ordered list of known NH for each IP prefix with the two first elements identifying the backup-group. The algorithm sends a routing update with a VNH whenever one of these elements change. Observe that the total number of backup-groups depends on the number of peers n the supercharged router has. Taking into account all the neighbors of the supercharged router, the total number of backup-groups is $\frac{n!}{(n-2)!}$. For instance, considering a router with 10 neighbors (a lot in practice), the number of backup-groups is only 90. In this paper, we worked with backup-group of size 2, which can protect from any single link or node failure. Our algorithm in general though and can compute backup-groups of any size.

Directing tagged traffic to the appropriate NH in the switch’s FIB. The controller provisions dedicated flow entries to match on the VMAC associated to each backup-group. By default, these rules direct the traffic to the primary NH. Upon a node or a link failure, all the backup-group entries for which the unreachable NH was the primary NH are rewritten to direct the traffic to the backup NH instead. In the worst case, the number of flow rewritings that has to be done is the number of peers of the supercharged router, *i.e.* a small constant value. Listing 2 describes how the controller determines what flow to install.

```
def data_plane_convergence(peer_down_id):
    for backup_nh in bck_groups[peer_down_id]:
        install_flow(
            match(dst_mac=bck_groups[peer_down_id][backup_nh].vmac),
            modify(dst_mac=get_mac(backup_nh)),
            fwd(output_port=get_port(backup_nh))
        )
```

Listing 2: Data-plane convergence procedure

3. IMPLEMENTATION

We now briefly describe a reliable implementation of a supercharged controller. All our source code is available at https://github.com/nsg-ethz/supercharged_router.

Controller. We built our prototype atop ExaBGP [13] as *BGP controller*, FreeBFD [14] as *BFD daemon* (failure detection), and Floodlight [15] as *SDN controller*.

ExaBGP enables us to establish BGP adjacencies and programmatically receive and send BGP routes over them. We extended ExaBGP with a complete implementation of the BGP Decision Process, the full algorithm to compute backup groups (see Listing 1) and the ability to rewrite BGP NH on-the-fly. FreeBFD provides a user-space implementation of the Bidirectional Forwarding Detection Protocol (BFD) [16]. We use it to speed up the discovery of peer failure. Upon a peer

failure announcement produced by FreeBFD, ExaBGP uses the REST API provided by Floodlight to push the corresponding rewrite rules in the data-plane (see §2). We also extended Floodlight with an ARP resolver in order to reply to the ARP queries generated by the router for resolving the virtual NH to the corresponding virtual MAC address.

Reliability. Any underlying SDN switch or any control-plane component of the supercharged controller can fail at any time. Since our goal is to enable fast convergence, our controller must be able to survive to any component failure to be of any use. Fortunately, reliability at both the data-plane and the control-plane is easily ensured.

At the data-plane level, reliability is obtained by using at least two SDN-enabled switches connected to each supercharged router. Observe that redundant SDN switches can be shared across multiple supercharged routers that share physical connectivity, reducing the costs. At the control-plane level, reliability is enforced by running at least 2 instances of the controller and connecting them to the corresponding supercharged router. Interestingly, no state needs to be synchronized across the backups as both backups will receive exactly the same input (BGP routes) and run the exact same deterministic algorithm and, hence, eventually compute the same outcome. The cost is the supercharged router to receive two copies of each route, and for the peers to configure an extra BGP session—slightly increasing the load in the control-plane. However, we note that control-plane memory is inexpensive (being classical DRAM) and routers maintain multiple BGP adjacencies already, for obvious redundancy reasons.

4. EVALUATION

We now present a thorough evaluation of the convergence time of a recent hardware router prior and after supercharging it using our prototype implementation. We then illustrate the scalability of our controller implementation using micro-benchmarks.

Setup and methodology. Our complete setup is depicted in Fig.4. It consists of 3 routers Cisco Nexus 7k C7018 (running NX-OS v6.2, with no hierarchical FIB) interconnected through a HP E3800 J9575A Openflow-enabled switch.

Using this setup, we measured the convergence time of $R1$ prior and after supercharging it. To do so, we loaded $R2$ and $R3$ with an increasing number of actual BGP routes collected from the RIPE RIS dataset [17]. Both $R2$ and $R3$ were loaded with the same feed to ensure that they both advertise the same set of prefixes. In both cases (supercharged and not supercharged), $R1$ was configured to prefer $R2$ for all the destinations. Once all routes were advertised, we started to inject traffic at $R1$ using a FPGA-based generator (see below).

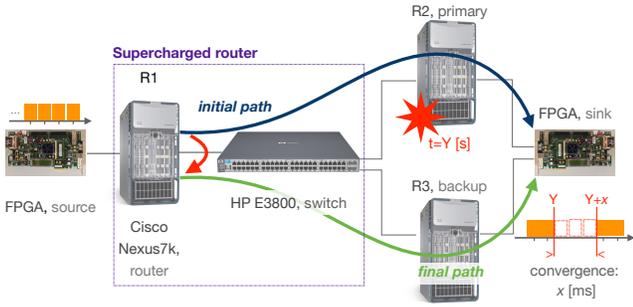


Figure 4: Overview of our HW-based convergence lab. $R2$ is rendered inaccessible, causing $R1$ to switch to $R3$ for every single prefixes. At the same time, we use FPGAs to precisely (μ s resolution) measure the convergence time. Ultimately, we compare the convergence time of the supercharged $R1$ and the standalone $R1$.

To compute a representative distribution of the convergence time across different prefixes, we generated traffic towards 100 IP addresses, randomly selected among the IP prefixes advertised by $R2$ and $R3$, and including the first and last prefix advertised. We configured $R2$ and $R3$ to send all receiving traffic to another FPGA-based board, acting as sink. To ensure that the same detection time in both experiments, we configured BFD on $R2$ on both experiments. We then disconnected $R2$ from the switch, triggering the convergence process at $R1$; subsequently, we measure the time until recovering full connectivity.

Custom-built hardware-based traffic generator. Since this project deals with *fast* convergence, we needed a way to accurately measure small convergence time. Our choice rapidly went to hardware-based measurement, using FPGA boards. Using the FPGAs, we were able to measure convergence time *with a precision of only 70 μ s*. Such a precision would be impossible to achieve using software-based measurements.

We measured the convergence time by monitoring the maximum inter-packet delays seen by each flow between two FPGA boards: a source and a sink. For the FPGA boards, we used a system-on-chip architecture with (i) an embedded MicroBlaze soft processor (ii) an Ethernet MAC core, and (iii) either a traffic generator (source) or traffic monitor (sink). The traffic monitor matches the destination IP to a content-addressable memory (CAM) containing the expected destination IPs, before it updates the corresponding maximum inter-packet delay. We implemented both, source and sink, on Xilinx ML605 evaluation boards featuring a Virtex-6 XC6VLX240T-1FFG1156 FPGA.

We programmed the source FPGA to continuously send a stream of 64-byte UDP packets to each of the 100 IPs over an 1G Ethernet connection. Doing so generated a traffic load of about 725 MBit/s, which corre-

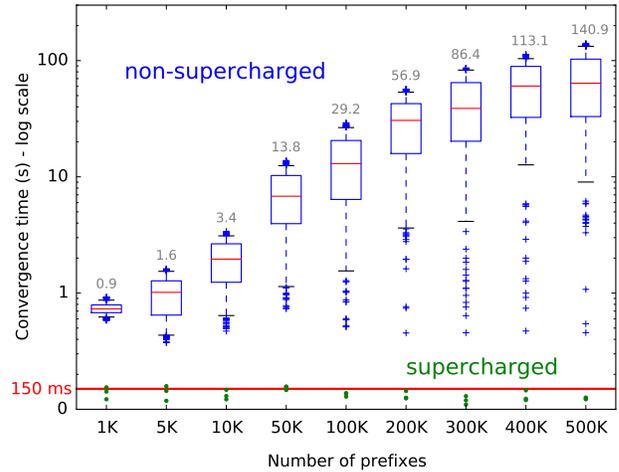


Figure 5: With respect to the normal convergence time which increases linearly with the number of prefixes, our supercharged router *systematically converged within 150ms*. In contrast, the non-supercharged router took more than 2 minutes to converge in the worst-case.

sponds to about 1.4M packets/s in total and 14K packets/s per flow.

The non-supercharged $R1$ took ~ 2.5 min to converge in the worst-case. Using the methodology above, we measured the convergence time of the router prior and after the supercharging process for an increasing number of prefixes (from 1k to 500k). We repeated the experiment 3 times per number of advertised prefixes. Since for each experiment, we measured the convergence of 100 prefixes, we ended up with 300 statistically representative data points per measurement. Fig. 5 depicts the distribution of the convergence time using box-plots; both the non-supercharged and supercharged routers are displayed. Each box shows the inter-quartile range of the convergence time; the line in the box depicts the median value; and the whiskers show 5th and 95th percentiles. The numbers on top are the maximal convergence time recorded.

For the non-supercharged $R1$, we can see that the convergence time is roughly linear² in the number of prefixes in the FIB. This is because FIB entries are updated one-by-one; while the first FIB entry is updated immediately, irregardless of the total number of prefixes, the last entry updated must wait for all the preceding FIB entries to be updated. This worst-case highlights undesirability of the non-supercharged approach: as the FIB grows, so does the convergence time. Here, we see that $R1$ took close than 2.5min to converge when loaded with 512k.

The supercharged $R1$ systematically converged within 150ms, for all prefixes. Thanks to its hier-

²The linearity of convergence time is not well reflected in Fig. 5 because of the non-uniform scaling of the x -axis.

archical FIB design, the supercharged R1’s convergence time was constant—irrespective of the number of prefixes. This is illustrated in Fig. 5 by a almost horizontal line around 150ms. With respect to the above worst-case, this constitutes a $900\times$ improvement factor. Interestingly, the worst-case convergence time of a supercharged router is still more than two times faster than the best-case convergence time of its standalone counterpart. Indeed, in the best case, it took 375 ms for the standalone R1 to update the first FIB entry.

The supercharged controller processed each BGP update under 125ms. While supercharging router drastically improves its data-plane convergence time, it slightly increases its control-plane convergence time due to the need to re-compute the backup-group upon every BGP announcement and, potentially, update the virtual NH. To quantify this overhead, we measured the time our unoptimized, python-based BGP controller took to process two times 500K updates from two different peers. In the worst-case, processing an update took 0.8s but the 99th percentile was only 125ms. We argue that this is a reasonable price to pay for improving the convergence by several orders of magnitude.

5. RELATED WORK

Routing. The problem of minimizing down time during convergence has been well studied in the domain of distributed routing protocols [18, 19, 20, 11]. Among all these works, BGP Prefix Independent Convergence (PIC) [11] is certainly the most relevant. PIC introduces the idea of using a hierarchical FIB design in order to speed-up router convergence upon peering link failure. In essence, our supercharged router replicates the functionality of PIC but on *any* routers (even old ones), without requiring expensive line-cards update.

SDN. FatTire [21] is a domain-specific language which aims at simplifying the design of fault-tolerant network programs that can quickly converge by leveraging fast-failover mechanisms provided in recent versions of OpenFlow [22]. While FatTire targets fully-deployed OpenFlow networks, we show that we can already speed up the convergence of existing network with a single SDN switch. In [23], Gamperli *et al.* evaluated the effect of centralization on BGP convergence. They showed that the convergence time decreases as more and more of the network-wide decision get centralized. Supercharging routers is a direct complement to their work. Once enough routers have been supercharged, one can use [23] at the network-level to speed-up convergence even more. Just as a supercharged router, SDX [8] is also an example of how routing and SDN can coexist in a symbiotic way, providing each other benefit. While SDX showed how router can boost SDN equipment performance, we show how SDN equipment can boost router

performance. Also, our technique can immediately be applied to the SDX environment in order to boost the convergence time upon the failure of an IXP participant equipment.

Incremental SDN deployment. RouteFlow [24] and Panopticon [25] proposed techniques to incrementally deploy SDN equipments in existing networks with the aim of reaping early benefits. RouteFlow enables operator to build fully-fledged IP router out of a SDN switch, while Panopticon enables to steer traffic away from a L2 domain to SDN equipment where it could be processed. In contrast to supercharging routers, none of them improve the performance of existing equipment. In [26], Agarwal *et al.* proposed a way to improve the Traffic Engineering (TE) performance of existing networks even in partial deployment of SDN capability, highlighting another aspect of the network that can be “supercharged” using SDN devices.

6. CONCLUSIONS

We boost the convergence time of legacy routers by combining them with SDN equipment in a novel way, essentially building a hierarchical forwarding table spanning across devices. Through thorough evaluations on real hardware, we demonstrated significant gains with convergence time reduced by up to $900\times$.

We believe this paper opens up many interesting future directions for integrating legacy routing and SDN devices in a more “symbiotic way”. By juxtaposing the agility of the SDN with the tried-and-true routers prevalent in the industry today, we take the best of both worlds and take the first steps towards electrifying modern day networks through supercharged networking devices.

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